
Oríon algo robo Documentation

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This wrapper provides access through [Oríon](#) to several Bayesian optimization algorithms in the library [RoBO](#).

This `orion.algo` plugin was generated with [Cookiecutter](#) along with [@Epistimio](#)'s `cookiecutter-orion.algo` template.

INSTALLATION

The RoBO wrapper is currently only supported on Linux.

Before installing RoBO, make sure you have `libeigen` and `swig` installed. On ubuntu, you can install them with `apt-get`

```
$ sudo apt-get install libeigen3-dev swig
```

One of the dependencies of RoBO does not declare its dependencies and therefore we need to install these dependencies first. The order of dependencies in `requirements.txt` reflects this order. To install them sequentially, use the following command

```
$ curl -s https://git.io/JLnCA | grep -v "^#" | xargs -n 1 -L 1 pip install
```

Finally, you can install this package using PyPI

```
$ pip install orion.algo.robo
```


CONTRIBUTE OR ASK

Do you have a question or issues? Do you want to report a bug or suggest a feature? Name it! Please contact us by opening an issue in our repository below and checkout Oríon's [contribution guidelines](#):

- Issue Tracker: <https://github.com/Epistimio/orion.algo.robo/issues>
- Source Code: <https://github.com/Epistimio/orion.algo.robo>

Start by starring and forking our Github repo!

Thanks for the support!

CITATION

If you use this wrapper for your publications, please cite both [RoBO](#) and [Oríon](#). Please also cite the papers of the algorithms you used, such as DNGO or BOHAMIANN. See the documentation of the algorithms to find corresponding original papers.

LICENSE

Distributed under the terms of the BSD-3-Clause license, `orion.algo.rob` is free and open source software.

4.1 RoBO Gaussian Process

```
experiment:
  algorithms:
    RoBO_GP:
      seed: 0
      n_initial_points: 20
      maximizer: 'random'
      acquisition_func: 'log_ei'
      normalize_input: True
      normalize_output: False
```

4.2 RoBO Gaussian Process with MCMC

```
experiment:
  algorithms:
    RoBO_GP_MCMC:
      seed: 0
      n_initial_points: 20
      maximizer: 'random'
      acquisition_func: 'log_ei'
      normalize_input: True
      normalize_output: False
      chain_length: 2000
      burnin_steps: 2000
```

4.3 RoBO Random Forest

```
experiment:
  algorithms:
    RoBO_RandomForest:
      seed: 0
      n_initial_points: 20
      maximizer: 'random'
      acquisition_func: 'log_ei'
      num_trees: 30
      do_bootstrapping: True
      n_points_per_tree: 0
      compute_oob_error: False
      return_total_variance: True
```

4.4 RoBO DNGO

```
experiment:
  algorithms:
    RoBO_DNGO:
      seed: 0
      n_initial_points: 20
      maximizer: 'random'
      acquisition_func: 'log_ei'
      normalize_input: True
      normalize_output: False
      chain_length: 2000
      burnin_steps: 2000
      batch_size: 10
      num_epochs: 500
      learning_rate: 1e-2
      adapt_epoch: 5000
```

4.5 RoBO BOHAMIANN

```
experiment:
  algorithms:
    RoBO_BOHAMIANN:
      seed: 0
      n_initial_points: 20
      maximizer: 'random'
      acquisition_func: 'log_ei'
      normalize_input: True
      normalize_output: False
      burnin_steps: 2000
      sampling_method: "adaptive_sghmc"
      use_double_precision: True
      num_steps: null
```

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```
keep_every: 100
learning_rate: 1e-2
batch_size: 20
epsilon: 1e-10
mdecay: 0.05
verbose: False
```